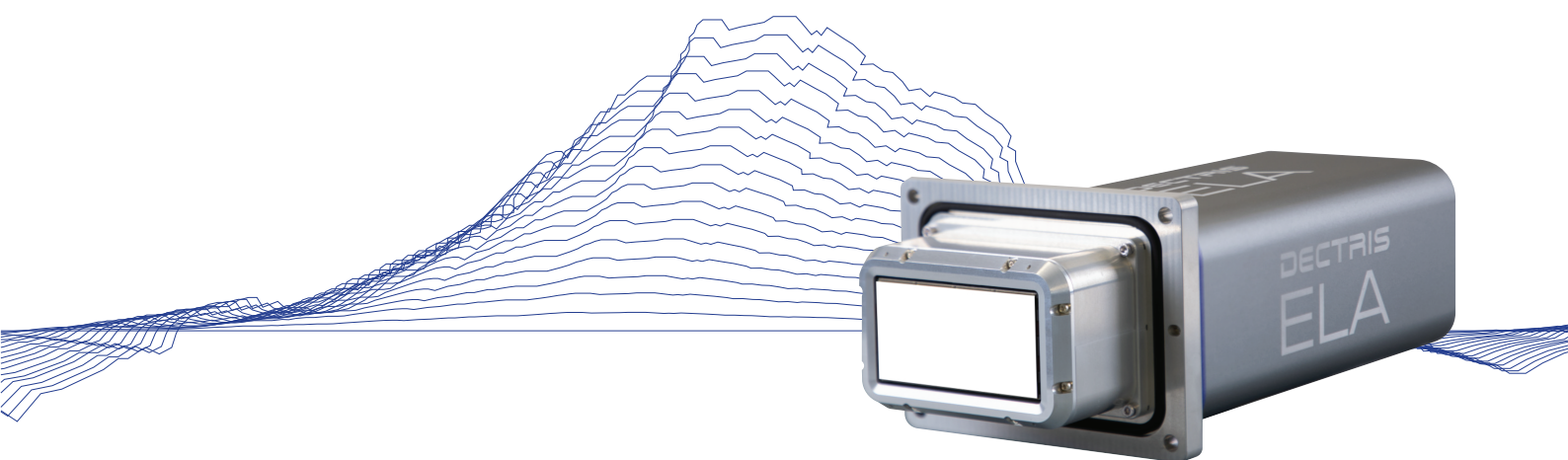


DECTRIS



User Manual DECTRIS ELA[®]

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CONTENT

CONTENT	i
1 GENERAL INFORMATION	1
1.1 Contact and Support	1
1.2 Explanation of Symbols	1
1.2.1 Symbols in the Manual	1
1.2.2 Symbols on the Detector	1
1.3 Warranty Information	2
1.4 Disclaimer	2
2 SAFETY INSTRUCTIONS	3
3 SYSTEM DESCRIPTION	4
3.1 Components	4
3.2 Hybrid Pixel Technology	4
3.2.1 Basic Functionality	4
3.2.2 Continuous Readout	4
3.2.3 Auto-Summation	4
3.2.4 Lines-ROI	5
3.2.5 Instant Retrigger	5
3.2.6 8-bit Readout	6
3.3 Software	6
3.3.1 Overview of SIMPLON API	6
4 QUICK START GUIDE	8
4.1 Accessing the Detector Control Unit	8
4.1.1 Using DHCP	8
4.1.2 Using a Fixed IP	9
5 GETTING STARTED	10
5.1 Startup Procedure	10
6 WEB INTERFACE	11
6.1 Overview	11
6.2 System Settings and Administration	12
7 GENERAL USAGE OF THE DETECTOR SYSTEM	13
7.1 Detector Control and Output	13
7.2 Recording an Image or an Image Series	13
7.3 Control of the Detector from a Specific Environment	14
7.3.1 Main Configuration Parameters	14
7.3.2 Additional Configuration Parameters	15
7.4 Interdependency of Configuration Parameters	17
7.4.1 Interdependency of Calibration Parameters	17
7.4.2 Interdependency of Timing Parameters	17
7.5 Examples	17
7.5.1 Curl	17
7.5.2 Python 3	19
8 TRIGGER USAGE	20
8.1 Introduction	20
8.2 INTS - Internal (Software) Triggering	20
8.3 INTE - Internal (Software) Enable	21
8.4 EXTS - Externally Triggered Exposure Series	22
8.5 EXTE - Externally Enabled Exposure Series	23

9	HDF5 AND ALBULA	25
9.1	ALBULA Overview	25
9.2	Third Party HDF5 Libraries	26
10	PIXEL MASK	27
10.1	Applying the pixel mask	27
10.2	Updating the pixel mask	27
10.2.1	Overview	27
10.2.2	Retrieving the current mask from the detector system	27
10.2.3	Manipulating the pixel mask	27
10.2.4	Uploading and storing the pixel mask	28
10.2.5	Python Example	28
11	FLATFIELD	29
11.1	Applying the flatfield	29
11.2	Creating a flatfield	29
11.2.1	Overview	29
11.2.2	Acquire uniformly-illuminated image	29
11.2.3	Upload pixel-wise correction factors	30

1. GENERAL INFORMATION

1.1. Contact and Support

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Should you have questions concerning the system or its use, please contact us via telephone, e-mail or fax.

1.2. Explanation of Symbols

1.2.1. Symbols in the Manual

Warning

#0



Warning blocks are used to indicate danger or risk to personnel or equipment.

Caution

#0



Caution blocks are used to indicate danger or risk to equipment.

Information

#0



Information blocks are used to highlight important information.

1.2.2. Symbols on the Detector

Attention

#0



Before operating the detector, please consult the user documentation.

Danger

#0



Touching the cover foil or sensors can cause an electrical shock. Disconnect power before servicing the detector!

1.3. Warranty Information

Caution

#1



Do not ship the system back before you receive the necessary transport and shipping information.

1.4. Disclaimer

DECTRIS® has carefully compiled the contents of this manual according to the current state of knowledge. Damage and warranty claims arising from missing or incorrect data are excluded.

DECTRIS® bears no responsibility or liability for damage of any kind, also for indirect or consequential damage resulting from the use of this system.

DECTRIS® is the sole owner of all user rights related to the contents of the manual (in particular information, images or materials), unless otherwise indicated. Without the written permission of DECTRIS® it is prohibited to integrate the protected contents in this publication into other programs or other websites or to use them by any other means.

DECTRIS® reserves the right, at its own discretion and without liability or prior notice, to modify and/or discontinue this publication in whole or in part at any time, and is not obliged to update the contents of the manual.

2. SAFETY INSTRUCTIONS

Caution

#2



Please read these safety instructions before operating the detector system.

- Before turning the power supply on, check the supply voltage against the label on the power supply. Using an improper main voltage will destroy the power supply and damage the detector.
- Power down the detector system before connecting or disconnecting any cable.
- Make sure the cables are connected and properly secured.
- Avoid pressure or tension on the cables.
- Operating the detector outside the specified ambient conditions could damage the system.
- Ensure that the detector is operated with a thermal stabilization unit.
- Ensure that the detector is switched off before pumping or venting the detector head. Operating the detector outside the specified pressure range could damage the system.
- Place the protective cover on the detector when it is not in use to prevent the detector from accidental damage.
- Opening the detector or the power supply housing without explicit instructions from DECTRIS® will void the warranty.
- Do not install additional software or change the operating system of the Detector Control Unit.
- Do not touch the sensor or contaminate any vacuum related part.

3. SYSTEM DESCRIPTION

3.1. Components

The ELA detector system consists of the following components:

- ELA detector
- Power supply for the detector
- Detector control unit
- Thermal stabilization unit¹
- Accessories
- Documentation

3.2. Hybrid Pixel Technology

3.2.1. Basic Functionality

DECTRIS® detectors provide direct detection of electrons with optimized solid-state sensors and CMOS readout ASICs in hybrid pixel technology. Well-proven standard technologies are employed independently for both the sensor and the CMOS readout ASIC. The detectors operate in single-electron counting mode and provide outstanding data quality. They feature very high dynamic range, zero dark signal and zero readout noise and hence achieve optimal signal-to-noise ratio at short readout time and high frame rates.

Key Advantages

- Direct detection of electrons
- Single-electron counting
- Excellent signal-to-noise ratio and very high dynamic range (zero dark signal, zero noise)
- Two 8 bit, 16 bit digital counters
- Short readout time and high frame rates
- Shutterless operation

The ELA hybrid pixel detector is composed of a sensor, a two-dimensional array of pn-diodes processed in a high-resistivity semiconductor, connected to an array of readout channels designed in advanced CMOS technology.

3.2.2. Continuous Readout

One of the hallmark features of ELA is its continuous readout that enables high frame rates at high duty cycles. Every pixel of an ELA ASIC features two digital counters. After acquisition of a frame, the pixels switch from counting in one digital counter to the other. While one counter is being read out, data acquisition continues in the other counter.

3.2.3. Auto-Summation

ELA auto-summation mode is a further benefit of continuous readout with high duty cycle. While a single frame is limited to the 8 bit, 16 bit of the digital counter, auto-summation extends the data depth up to 32 bit, or more than 4.2 billion counts per pixel, depending on the number of summed frames in an image. At short exposure times and high frame rates, all counts are captured in the digital counter of a pixel and directly read out as an image. If long exposure times are requested, frames are still acquired at high rates on the pixel level, effectively avoiding any overflows. The detector system sums the frames to images on the fly, extending the bit depth of the data by the number of summed frames.

¹ Some systems might be delivered without a thermal stabilization unit. Please consult the Technical Specifications for more information.

3.2.4. Lines-ROI

The Lines-ROI® feature allows to read out a user-defined area of the sensor equivalent to a selected number of lines (pixel rows) counted along the y axis, extending over the full horizontal length of the detector. A schematic representation of the readout area is give in figure 3.1.

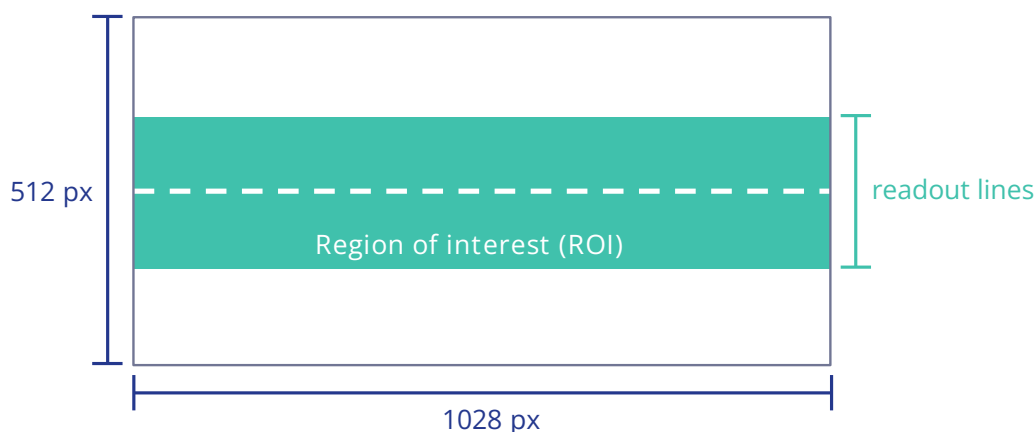


Figure 3.1: Readout area in Lines-ROI® mode

A list of the highest framerates at specific settigs is given in the table below.

Table 3.1: Highest achievable framerates in ROI mode

readout lines	image size [w × h]	readout bit-depth	highest framerate
512	1028 px × 512 px	16 bit	2 250 fps
512	1028 px × 512 px	8 bit	4 500 fps
256	1028 px × 256 px	16 bit	4 500 fps
256	1028 px × 256 px	8 bit	9 000 fps
128	1028 px × 128 px	16 bit	9 000 fps
128	1028 px × 128 px	8 bit	18 000 fps

For more information on how to enable this feature via the SIMPLON API please refer to section 7.3.2.

3.2.5. Instant Retrigger

ELA detectors feature the DECTRIS INSTANT RETRIGGER® technology for improved high-rate counting performance. The Instant Retrigger capability results in non-paralyzable counting and allows for enhanced count-rate correction.

DECTRIS INSTANT RETRIGGER® with adjustable dead time is a electron counting imaging method that results in non-paralyzable counting and achieves an improved high-rate counting performance. In a conventional hybrid-pixel detector, the charge pulses generated by impinging electrons are counted by digital circuits. Simultaneously generated pulses can pile up and result in electron counts being lost. At high electron fluxes, pulse pile-up significantly affects the observed count rate and can lead to complete paralyzation of the counting circuit. In ELA detectors, the Instant Retrigger re-evaluates the pulse signal after a predetermined dead-time interval after each count and is able to retrigger the counting circuit should a pulse pile-up occur. The dead time interval is adjustable and is equivalent to the width of one single electron pulse. This results in non-paralyzable counting and allows for enhanced count-rate correction so as to achieve improved data quality at high count rates.

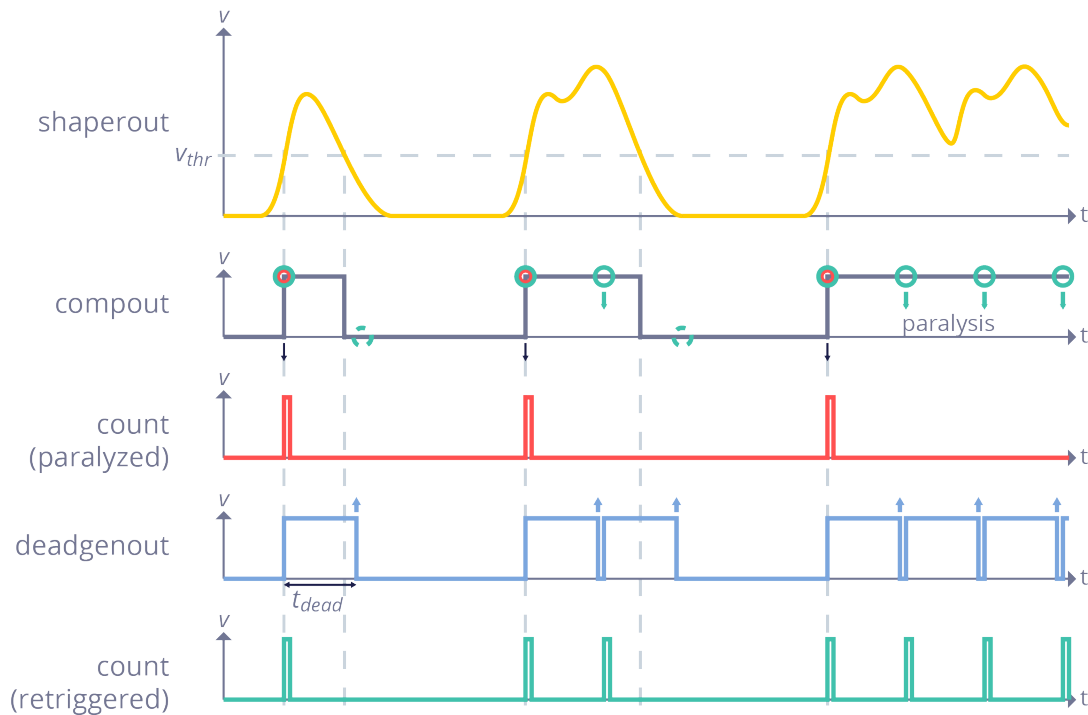


Figure 3.2: Signal Waveforms Illustrating the DECTRIS INSTANT RETRIGGER® technology

The Instant Retrigger principle is illustrated in figure 3.2. The first diagram shows the signal pulses generated by impinging electrons and the effective discriminator threshold level for single electron counting. The pulse signal includes a series of one single pulse, a pile-up of two pulses and a pile-up of multiple pulses. The second diagram shows the corresponding digital discriminator output signal that triggers the counting circuit. The third diagram shows the corresponding counts being registered by a conventional single electron counting detector, clearly illustrating that counts are lost in the case of pulse pile-up and that this can lead to paralyzation. The fourth diagram shows the respective dead-time generator output signal provided by a single electron counting detector with Instant Retrigger. Here, a predefined dead time interval is started whenever a count has been registered. The fifth diagram shows the corresponding counts being registered, including potential retriggering of the counting circuit after the dead-time interval after each count. This clearly illustrates that pulses are counted more accurately in the case of pile-up and that counting is non-paralyzable.

3.2.6. 8-bit Readout

The DECTRIS ELA® ASIC allows the option to read out only the first 8 bits of every counter instead of the full 16 bits. This enables a higher maximum frame rate at the cost of a lower dynamic range. The 8-bit mode is automatically enabled as soon as the frame rate exceeds the maximum frame rate in 16-bit mode, as indicated in the Technical Specifications.

When using the 8-bit mode, it is important not to exceed the maximum flux per pixel, as there is no overflow protection and the counter will roll over if 255 counts are exceeded. This means the maximum flux per pixel is $255 \times \text{frame rate}$ in 8-bit mode.

3.3. Software

3.3.1. Overview of SIMPLON API

The ELA detector system is controlled via the SIMPLON API, which relies on a http/REST interface. The API Reference is provided as a separate document "SIMPLON API Reference".

The detector's web interface (chapter 6) gives access to fundamental settings and status parameters and also enables a first test to see if the detector system has been set up properly (after installation and startup as described in chapters 4 and 5).

The ELA detector writes images in the HDF5 file format (chapter 9). DECTRIS® provides the image viewer ALBULA, which is able to handle the HDF5 images, with the primary aim to display them. ALBULA is available free of charge for the platforms Linux and Windows (for download please go to <http://www.dectris.com>). The

ALBULA version for Linux and Windows comes with a Python API for handling the HDF5 files that allows performing arithmetic operations on image data as well as basic analysis. Furthermore, the API enables seamless integration of the viewer into an existing infrastructure. More information on HDF5 and ALBULA is given in chapter 9.

4. QUICK START GUIDE

4.1. Accessing the Detector Control Unit

The ELA detector is controlled via the network interface of the detector control unit. Hence, the IP network address of the detector control unit has to be known to be able to connect to the API. Depending on the network structure, there are several ways of determining the IP network address, which are described below.

- See the Technical Specifications for the default network port configuration of your detector control unit.
- The default network port configuration may be changed through the detector's web interface (see section 6.2).

4.1.1. Using DHCP

If there is a DHCP server available on the network, plug the network cable into a port of the detector control unit pre-configured for DHCP. See the Technical Specifications for the default network port configuration of your detector control unit.

To determine the IP of your detector, plug in a keyboard and monitor to the detector control unit and power it up. Then follow the following steps:

- Once the detector control unit is fully booted, a command line login prompt will appear.
- Type `recovery` and press return.
- If a password prompt appears, leave it empty and press return. The login name was most likely misspelled, restart from point 1.
- Type `i` to select option (i) show ip addresses.
- The IP address will be displayed on the screen.
- If no IP is displayed, make sure that the DCU is properly connected to your network.

Alternatively, the IP network address can be retrieved by searching for the MAC address on the network. For network safety reasons, please ask the network administrator for assistance in obtaining the IP address. If you are the network administrator or have the required permission, the following Linux command can be used to retrieve the IP network address:

`[]$ _ Linux Command`

```
sudo nmap -sP xxx.xxx.xxx.xxx/24 | awk '/^Nmap/{ip=$NF}/yy:yy:yy:yy:yy:zz/{print ip}'\ \
```

where `xxx.xxx.xxx.xxx/24` is the network address range to be scanned (e.g. `192.168.0.1/24`) and `yy:yy:yy:yy:yy:zz` is the MAC address of the DHCP network port in the back of the detector control unit. You can find the MAC address of the port using the method described below.

Determining the MAC Address of a Port

The MAC address of the first network port can be found on the bottom of the service tag label (pull-out label in the front of the detector control unit, the correct address is the EMBEDDED NIC 1 MAC ADDRESS). The MAC addresses of the second, third and fourth ports are the same as the first one, but with the last two digits incremented by `zz+2`, `zz+4` and `zz+6`, respectively. E.g. if the first port is `01:23:45:67:89:ab`, then the second port is `01:23:45:67:89:ad` (make sure to use the hexadecimal system).

4.1.2. Using a Fixed IP

If you want to access the detector control unit using a fixed IP network address, plug the network cable into the service port of your detector control unit pre-configured for a fixed IP. See the Technical Specifications for the network port configuration of your detector control unit and configure your network accordingly.

If you use e.g., a laptop to access the detector control unit directly for the initial configuration, you can use the following network settings on the laptop:

Table 4.1: Network Settings Laptop

IP Adress	169.254.254.100
Subnet Mask	255.255.0.0
Default Gateway	not required

With those settings, the detector can be easily configured through the web interface at <http://169.254.254.1>.

5. GETTING STARTED

Information

#1



Before operating the detector, read the complete documentation.

Warning

#1



Pay attention to **POWER OFF** the detector by disconnecting the power supply before pumping or venting the detector chamber.

5.1. Startup Procedure

- Ensure that the detector is installed at the Transmission Electron Microscope by qualified personnel and the detector chamber is evacuated. See Technical Specifications for required vacuum conditions.
- Connect and turn on the thermal stabilization unit. Set the operation temperature as specified in the Technical Specifications.
- Ensure that all cables are connected between detector and detector control unit
- Power on the detector. Pay attention not to power on the detector outside the specified temperature and pressure range.
- Turn on the detector control unit. Please allow at least 5 minutes for the BIOS test procedures and startup of software to complete.

6. WEB INTERFACE

6.1. Overview

The ELA web interface (figure 6.1) provides simple access to basic functions and settings of the detector system for installation, debugging, and system updates. For productive operation of the detector, please refer to the API Reference.

Table 6.1 summarizes the functions available through the left panel of the web system interface.

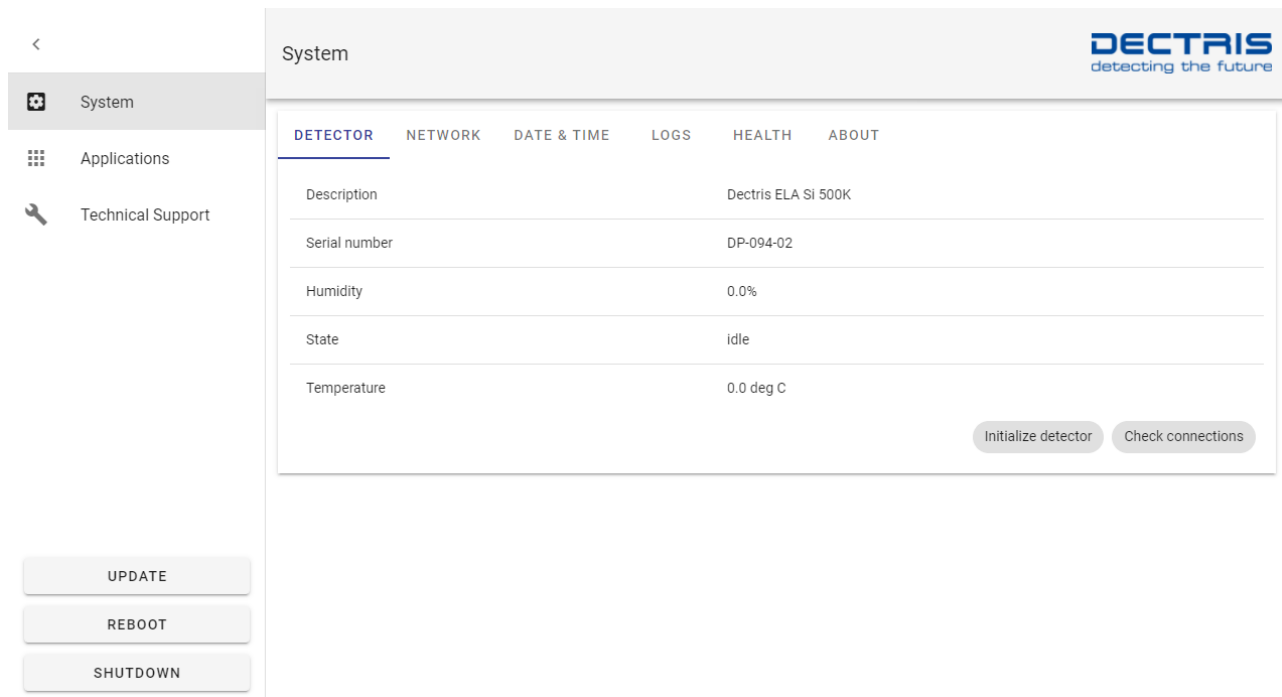


Figure 6.1: Homepage of web interface

Table 6.1: Menu items of the ELA web interface.

Menu Point	Content
System	View the system information and access the detector control unit system settings (see section 6.2)
Applications	Manage the detector and calibration applications. This tab provides functions to start and stop the detector software, change software versions and upgrade the detector software to a new version.
Technical Support	Simple interface to create a bug-report. The bug-report creates a tarball that can be downloaded and sent to DECTAIS® support at support@dectris.com. The bug report is not sent automatically. A step-by-step instruction on how to create a bug-report is given in the Technical Specifications.

6.2. System Settings and Administration

To access the ELA system settings, click on the corresponding tab on the homepage. The system tab allows to configure the detector control unit network settings and get some status and system information.

Table 6.2 summarises menu items available for configuration

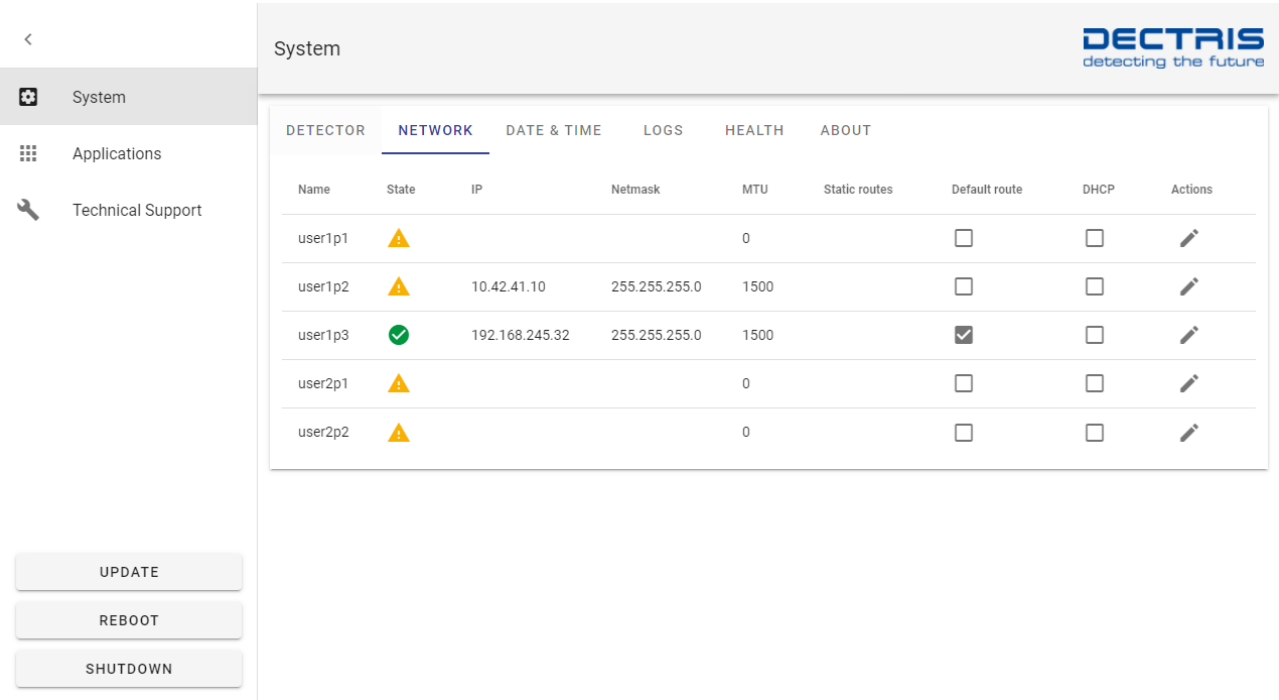


Figure 6.2: Screenshot of the system settings showing the network configuration page.

Table 6.2: Menu Items for Configuration/Testing

Detector	See the detector status and initialize the detector. The detector status can only be read out when the detector is initialized and the detector application is running. This tab also provides a way to quickly check the quality of the detector connection using the "Check connections" button. Typical values are above 0.15 mW for the TX power and above 0.3 mW for the RX power.
Network	Configure the user accessible network interfaces.
Date & Time	Configure date and time on the detector control unit. Provides the possibility to add an NTP server.
Logs	Select and view detector logs, including error, warning and debugging information.
Health	View system health information like board errors.
Information#2  ELA does not include a temperature / humidity sensor. As a result, the web interface will consistently display zero for both temperature and humidity.	
About	Display system details.

7. GENERAL USAGE OF THE DETECTOR SYSTEM

7.1. Detector Control and Output

The ELA detector system is controlled through the SIMPLON API, an interface to the detector that is based on the http protocol and implemented on the detector control unit. The API Reference supplied with the system describes this interface in detail and allows for easy integration of the detector control into the user instrumentation independent of the operating system or programming language being used. Please refer to the API Reference for details.

The data recorded by the detector can be accessed in different ways. Images can be stored by the filewriter on the detector control unit as HDF5 files. HDF5 files include detector metadata in a NeXus-compatible format. Buffered files have to be regularly fetched and subsequently deleted on the detector control unit as buffer space is limited¹.

Data can also be fetched through the stream interface, which relies on the ZeroMQ² distributed messaging protocol. The stream has a low latency and offers utmost flexibility. The metadata is transferred as part of the header. Streamed data is not buffered and will be lost if not fetched or incompletely fetched. Additional documentation is available at <https://github.com/dectris/documentation>.

Lastly, the monitor interface provides images as raw tiff files with minimal metadata. This is a low performance and low bandwidth interface, which allows to retrieve the latest recorded image for monitoring purposes during acquisitions. The monitor offers a relatively small buffer. In case of buffer overflow, the oldest images will be overwritten.

The interfaces do not preclude each other and can be activated simultaneously.

7.2. Recording an Image or an Image Series

Information

#3



Data might have to be fetched concurrently to a running image series. The lifespan of the data on the detector control unit is dependent on the configuration of your system as well as the interface used for collecting data. Data not fetched within this lifespan is permanently lost.

To record images or image series, the following steps need to be performed through the SIMPLON API (see the API Reference for details).

1. Make sure the detector has been set up according to the steps described in chapter 5.
2. Initialize the detector if this has not yet been done. The detector does not need to be reinitialized unless the detector entered an error status.
3. Set the detector parameters for data acquisition and configure the desired output interface (filewriter and/or stream and/or monitor interface). A list of essential configuration parameters can be found in section 7.3.1.
4. Arm the detector
5. Record the image or image series.
 - Send trigger(s) to record the image or image series as previously configured.
 - Fetch data through the data interface(s).
6. Disarm the detector (to ensure files are finalized and closed).
7. Repeat from step 3 for further data acquisition with different settings or to step 4 for identical settings.

¹ Buffer space varies dependent on the configuration of your system, buffer overflow will cause loss of data. See API Reference for further details.

² ZeroMQ distributed messaging (<http://zeromq.org/>)

7.3. Control of the Detector from a Specific Environment

Integrating the detector into a specific environment requires understanding of the necessary detector functions. The API reference will list all possible commands and features, but it does not give an explanation of the required functionality. Sections 7.3.1 and 7.3.2 cover a selection of essential and situational parameters respectively.

7.3.1. Main Configuration Parameters

The parameters described in this section allow control of the detector and data acquisition. Data will be acquired, however further configuration of the interface for data retrieval might be necessary depending on your set up. For starting a data acquisition, only the following parameters need to be adjusted.

- detector | config | nimages
- detector | config | count_time
- detector | config | frame_time
- detector | config | incident_energy

The detector configuration parameter `incident_energy` has to be set to the electron energy used for the experiment. The difference between the timing parameters `frame_time` and `count_time` has to be greater than the `detector_readout_time`. The `detector_readout_time` can be read back from the API. `Count_time` refers to the actual time the detector counts electrons and `frame_time` is the interval between acquisitions of subsequent frames (i.e. period). The number of images in a series of images, after a trigger, is configured with the parameter `nimages`. The detector always considers a trigger as the start of a series of `n` images. For example a single image is considered as a series of images containing 1 image. Once the detector has been armed a series can be started by issuing a trigger command or triggering the detector using an electronic pulse on the external trigger input (ExtIn). To switch between the trigger modes (see chapter 8) one can use the configuration parameter `trigger_mode`.

- detector | config | trigger_mode
- detector | config | ntrigger

Setting values greater than 1 for `ntrigger` allows several trigger commands or external trigger pulses per arm/disarm sequence. This mode allows recording several series of `nimages` with the same parameters. The resulting number of frames is product of `ntrigger` and `nimages`. In external enable modes the parameter `nimages` is ignored (i.e. always 1) and the number of frames therefore has to be configured using the detector configuration parameter `ntrigger`.

Information

#4



Please note that data be retrieved in different ways. For details, please see the API Reference.

With the filewriter enabled, the acquired data is written into HDF5 files. The filewriter has the following important configuration parameters:

- filewriter | config | name_pattern
- filewriter | config | nimages_per_file
- filewriter | config | compression_enabled

The filewriter parameter `name_pattern` sets the name template/pattern for the HDF5 files. The pattern `"$id"` is replaced with a sequence identification number and therefore can be used to discriminate between subsequent series. The sequence identification number is reset after initializing the detector. The parameter `nimages_per_file` sets the number of images stored per data file. A value of 1000 (default) means that for every 1000th image, a data file is created. If for example, 1800 images are expected to be recorded, the arm, trigger, disarm sequence means that a master file is created in the data directory after arming the detector. The trigger starts the image series and after 1000 recorded images one data container is made available on the buffer of the detector control unit. No further files will be made available until the series is finished either by completing the `n`th image (`nimages`) of the `n`th trigger (`ntrigger`) or by ending the series using the detector command `disarm`. As soon as either criteria is met the second data container is closed and made available for fetching.

7.3.2. Additional Configuration Parameters

Caution

#3



The following parameters are for special conditions and should be set with care and with understanding of the consequences. Changing these parameters to non-default values can have a substantial negative impact on data quality!

Corrections are enabled by default, but can be turned off using the following detector configuration parameters. In the vast majority of experiments data quality benefits from the data corrections. Therefore, disabling either correction will likely result in inferior data quality.

- detector | config | countrate_correction_applied
- detector | config | flatfield_correction_applied
- detector | config | pixel_mask_applied

The ROI mode (see section 3.2.4) offers high framerate by reducing the readout area and/or the number of bits per pixel. It is disabled by default. For using the ROI mode the following configuration parameters need to be adjusted:

- detector | config | roi_mode
- detector | config | roi_bit_depth
- detector | config | roi_y_size

To activate the Region of Interest (ROI) mode, set the `roi_mode` parameter to `"lines"`. The `roi_bit_depth` parameter specifies the number of bits per pixel, with options for 8 or 16. Operating in 8-bit mode is necessary for achieving the highest specified framerate. The resulting y-size (number of readout lines) of the image is determined by the `roi_y_size` parameter, while the x-size remains unchanged compared to when ROI mode is disabled. To deactivate ROI mode, set the `roi_mode` configuration parameter to `"disabled"`.



When using the 8-bit mode, it is important not to exceed the maximum flux per pixel, as there is no overflow protection and the counter will roll over if 255 counts are exceeded. This means the maximum flux per pixel is $255 \times \text{frame rate}$ in 8-bit mode.

A Python example on how to enable the ROI mode and take a single image with the filewriter interface is given below. The example assumes the IP address of the DCU to be 169.254.254.1. The acquired image can be downloaded via browser at <http://169.254.254.1/data>.

Example taking an image with ROI mode enabled

```
import json
import requests

# Simple detector client
class DetectorClient:
    def __init__(self, ip, port):
        self._ip = ip
        self._port = port

    def setConfig(self, param, value, module = 'detector'):
        url = f'http://{self._ip}:{self._port}/{module}/api/1.8.0/config/{param}'
        self._request(url, data = json.dumps({'value': value}))

    def sendCommand(self, param, module = 'detector'):
        url = f'http://{self._ip}:{self._port}/{module}/api/1.8.0/command/{param}'
        self._request(url)

    def _request(self, url, data={}, headers={}):
        reply = requests.put(url, data=data, headers=headers)
        assert reply.status_code in range(200, 300), reply.reason

if __name__ == '__main__':
    # Create DetectorClient instance and initialize the detector
    client = DetectorClient('169.254.254.1', '80')
    client.sendCommand('initialize')

    # Enable filewriter interface and set filename
    client.setConfig('mode', 'enabled', 'filewriter')
    client.setConfig('name_pattern', 'roi_test_${id}', 'filewriter')

    # Enable Lines-ROI and set ROI format
    client.setConfig('roi_mode', 'lines')
    client.setConfig('roi_bit_depth', 8)
    client.setConfig('roi_y_size', 256)

    # Set count and frame time
    client.setConfig('count_time', 1/9000)
    client.setConfig('frame_time', 1/9000)

    # Arms, triggers and disarm the detector
    client.sendCommand('arm')
    client.sendCommand('trigger')
    client.sendCommand('disarm')
```

Further parameters and their function are described in the API Reference.

7.4. Interdependency of Configuration Parameters

7.4.1. Interdependency of Calibration Parameters

The following calibration parameters have an implied or direct dependency. Changing either of the parameters might influence other parameters in the list.

Changing `incident_energy` or changing the `counting_mode` causes a reset of the flatfield.

- detector | config | `incident_energy`
- detector | config | `counting_mode`

The detector is shipped without flatfields. To ensure optimal data quality the user is encouraged to upload custom flatfields on the detector. More information on how to upload custom flatfields is given in chapter 11. The detector will be shipped with a factory calibrated `pixel_mask` mask where all defective pixels are flagged to be excluded from further processing. Updating values in the `pixel_mask` is described in chapter 10.

- detector | config | `flatfield`
- detector | config | `pixel_mask`

7.4.2. Interdependency of Timing Parameters

The following parameters are essential for exposure timing. Changing either values might influence other values in the list.

- detector | config | `detector_readout_time`

`detector_readout_time` may change if `incident_energy` is changed.

- detector | config | `frame_time`

If `frame_time` conflicts with the current `count_time`, `count_time` is set to the difference of `frame_time` and `detector_readout_time`. The auto summation parameter `frame_count_time` may be updated as well.

- detector | config | `count_time`

If `count_time` conflicts with `frame_time`, `frame_time` is set to the sum of `count_time` and `detector_readout_time`. The auto summation parameter `frame_count_time` may be updated as well.

Information

#6



To acquire images with a certain frame rate and best possible duty cycle, a simple procedure is to first set `count_time` to the inverse of the frame rate and subsequently `frame_time` to the inverse of the frame rate.

7.5. Examples

7.5.1. Curl

CURL, an abbreviation for Client for URLs, is a robust command-line tool designed for making HTTP requests. It is compatible with most operating systems and serves as an effective means of interacting with the SIMPLON API. Below, several example CURL command prompts are provided to illustrate how to read and write detector settings, as well as interface files stored on the DCU. The examples assume the IP address of the DCU to be 169.254.254.1.

Commands can be transmitted using a PUT request.

[]\$_ CURL Examples

Rebooting the DCU

```
curl -X PUT http://169.254.254.1/system/api/1.8.0/command/reboot
```

Initializing the detector

```
curl -X PUT http://169.254.254.1/detector/api/1.8.0/command/initialize
```

Arm the detector for acquisition

```
curl -X PUT http://169.254.254.1/detector/api/1.8.0/command/arm
```

Send a software trigger signal

```
curl -X PUT http://169.254.254.1/detector/api/1.8.0/command/trigger
```

Configuration parameters are modifiable through PUT requests with an additional payload and retrievable via GET requests in the SIMPLON API. As the API primarily uses JSON as the default encoding, it is essential that the payload of a PUT request be in the form of a JSON-encoded string.

[]\$_ CURL Examples

Set parameter of configuration key e.g. setting the incident_energy to 80 keV

```
curl -X PUT -d '{"value":80000}' -H "Content-Type:application/json" http://169.254.254.1/detector/api/1.8.0/config/incident_energy
```

Read configuration key of e.g. incident_energy

```
curl -X GET http://169.254.254.1/detector/api/1.8.0/config/incident_energy
```

The filewriter interface facilitates the creation of HDF5 files compatible with applications like NOVENA® or ALBULA. Activation of the interface is a manual process, and if desired, a filename can be specified. Once an acquisition is completed with the filewriter interface enabled, the buffered HDF5 files become accessible on the DCU. Users can then conveniently download or delete these files as needed.

[]\$_ CURL Examples

Enable the filewriter interface

```
curl -X PUT -d '{"value": "enabled"}' -H "Content-Type:application/json" http://169.254.254.1/filewriter/api/1.8.0/config/mode
```

Change the filename to 'example_file'

```
curl -X PUT -d '{"value": "example_file"}' -H "Content-Type:application/json" http://169.254.254.1/filewriter/api/1.8.0/config/name_pattern
```

Request a list of all filewriter files on the DCU

```
curl -X GET http://169.254.254.1/filewriter/api/1.8.0/status/files
```

Download 'example_file_master.h5' file from DCU

```
curl -X GET http://169.254.254.1/data/example_file_master.h5 --output example_file_master.h5
```

Delete filewriter file 'example_file_master.h5' on DCU

```
curl -X DELETE http://169.254.254.1/data/example_file_master.h5
```

7.5.2. Python 3

Python offers a convenient and versatile approach for operating the detector through the SIMPLON API. Below is an example Python script that uses the DEigerClient class to operate the detector through the SIMPLON API. The example assumes the IP address of the DCU to be 169.254.254.1.

Python DEigerClient example

```
from DEigerClient import DEigerClient

# Create an instance of the client
client = DEigerClient('169.254.254.1')

# Initialize the detector (only needed once)
client.sendDetectorCommand('initialize')

# Enables the filewriter interface and change the name_pattern to 'example_file'
client.setFileWriterConfig('mode', 'enabled')
client.setFileWriterConfig('name_pattern', 'example_file')

# Set detector configuration parameters (10 images with 0.1 s exposure time each)
client.setDetectorConfig('nimages', 10)
client.setDetectorConfig('count_time', 0.1)
client.setDetectorConfig('frame_time', 0.1)

# Arm the detector, trigger the acquisition and disarm the detector
client.sendDetectorCommand('arm')
client.sendDetectorCommand('trigger')
client.sendDetectorCommand('disarm')

# Download the files from the DCU to the current folder
client.fileWriterSave('example_file_master.h5', '.')
client.fileWriterSave('example_file_data_000001.h5', '.')

# Delete files on DCU
client.fileWriterFiles('example_file_master.h5', 'DELETE')
client.fileWriterFiles('example_file_data_000001.h5', 'DELETE')
```

8. TRIGGER USAGE

8.1. Introduction

Caution

#4



If the settings or the external trigger/enable pulses applied are out of specification, acquisitions will not be performed and the measurement obtained with the detector might be incomplete. All values used in the example are for demonstrational purposes only and should be adapted to meet the requirements of your application.

In order to record an image or a series of images, the ELA detector has to be initialized, configured, armed, and the exposure(s) started by a trigger signal. The steps necessary to record an image series are comprehensively described in chapter 5 and section 7.2. The detector can be triggered through software (internal trigger) or by an externally applied trigger signal (external trigger). Four different trigger modes are available and described in the following sections 8.2 to 8.5.

8.2. INTS - Internal (Software) Triggering

An exposure (series) can be triggered by using a software trigger. This is the default mode of operation.

Example detector configuration for internally triggered exposure series:

detector config trigger_mode	{"value": "ints"}
detector config nimages	{"value": 10}
detector config ntrigger	{"value": 3}
detector config frame_time	{"value": 1}
detector config count_time	{"value": 0.7}

The detector starts the first exposure after the trigger command has been received and processed¹. All subsequent frames are triggered according to the configuration of the frame_time and count_time parameters. The detector records nimages frames per trigger and stays armed until ntrigger are received. Figure 8.1 depicts an internally triggered series defined by frame_time, count_time and nimages.

¹ As the trigger command is sent over an TCP/IP connection the exact latency of the start of the exposure is hard to predict.

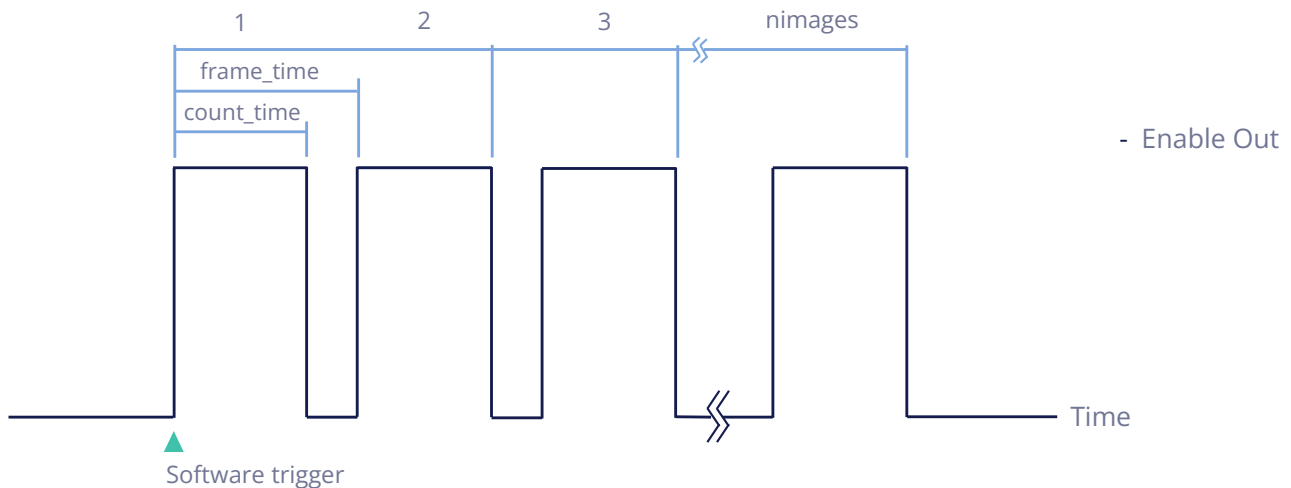


Figure 8.1: Series of exposures, defined by frame_time, count_time and nimages, triggered by a software trigger.

8.3. INTE – Internal (Software) Enable

In the trigger_mode 'inte' a single image or series of images with varying exposure times can be started by issuing a number ntrigger of trigger commands. Unlike the trigger_mode 'ints', the 'inte' trigger commands take an (optional) argument containing the count_time for the subsequent frame. In all enable modes the detector configuration parameter nimages is implied to be 1. The number of frames in a series therefore is solely based on the value of the parameter ntrigger.

Information

#7



The configured count_time and frame_time should be close to the count time and frame time of the shortest expected exposure in the configured series. The set count_time will be used to calculate internal auto-summation configuration values (section 3.2.3). In most situations a reasonable estimate of these values is sufficient.

Example detector configuration for an internally enabled exposure series:

detector config trigger_mode	{"value": "inte"}
detector config nimages	{"value": 1}
detector config ntrigger	{"value": 3}
detector config frame_time	{"value": 1.0} (see 7)
detector config count_time	{"value": 0.7} (see 7)

The detector starts the first exposure after a trigger command has been received and processed². All subsequent frames have to be triggered by individual trigger commands with an (optional) argument containing the count_time of the triggered frame. The detector stays armed until ntrigger are issued or the detector is disarmed. Figure 8.2 depicts an internally enabled exposure series defined by count_time (payload of the trigger command) and ntrigger. To record the same series an example sequence of commands is shown below.

detector command arm	
detector command trigger	{"value": 0.7}

² As the trigger command is sent over an TCP/IP connection the exact latency of the start of the exposure is hard to predict.

detector command trigger	{"value": 2.1}
⋮	
detector command trigger	{"value": 0.7}

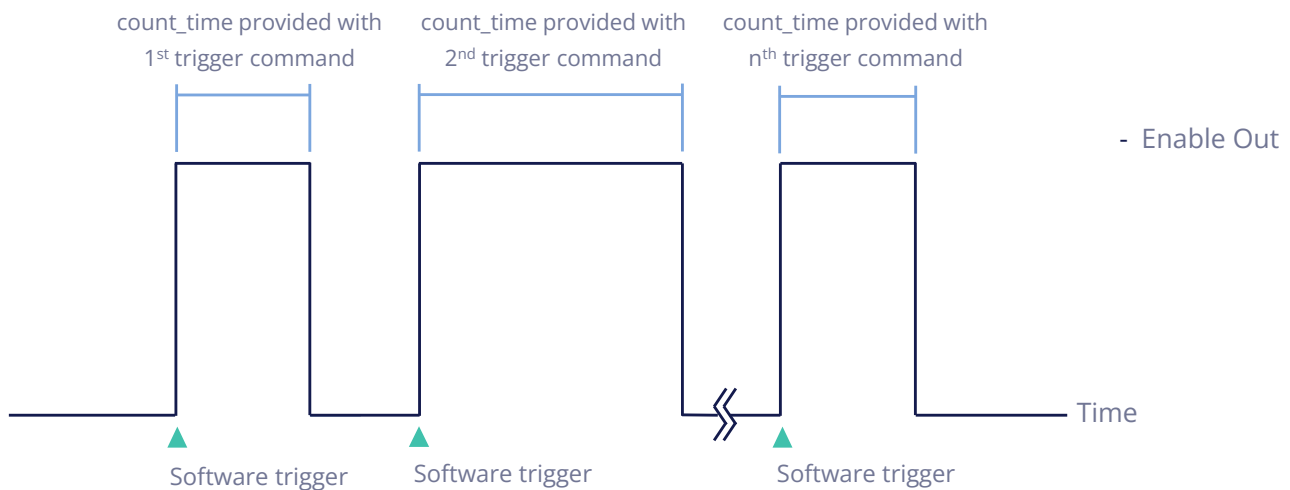


Figure 8.2: Series of exposures, defined by `count_time` (payload of the trigger command) and `ntrigger`, triggered by a software trigger.

8.4. EXTS - Externally Triggered Exposure Series

Caution

#5



Consult the Technical Specifications for details about the required electrical characteristics of the trigger signal.

The ELA detector systems also support external triggering. In the `trigger_mode` 'exts', `nimages` are recorded per trigger until `ntrigger` are received. Both `count_time` as well as `frame_time` are defined by the configuration. Example detector configuration for externally triggered exposure series:

detector config trigger_mode	{"value": "exts"}
detector config nimages	{"value": 10}
detector config ntrigger	{"value": 1}
detector config frame_time	{"value": 1.0}
detector config count_time	{"value": 0.7}

After the detector has been initialized, configured, and armed the acquisition can be triggered by a single external trigger pulse. The detector starts exposing after the (electrical) trigger signal has been issued. All subsequent frames are internally triggered according to the information previously configured by the `frame_time` and `count_time` parameters. The detector records `nimages` frames and stays armed until `ntrigger` are received.

Figure 8.3 depicts an externally triggered series defined by frame_time, count_time and nimages.

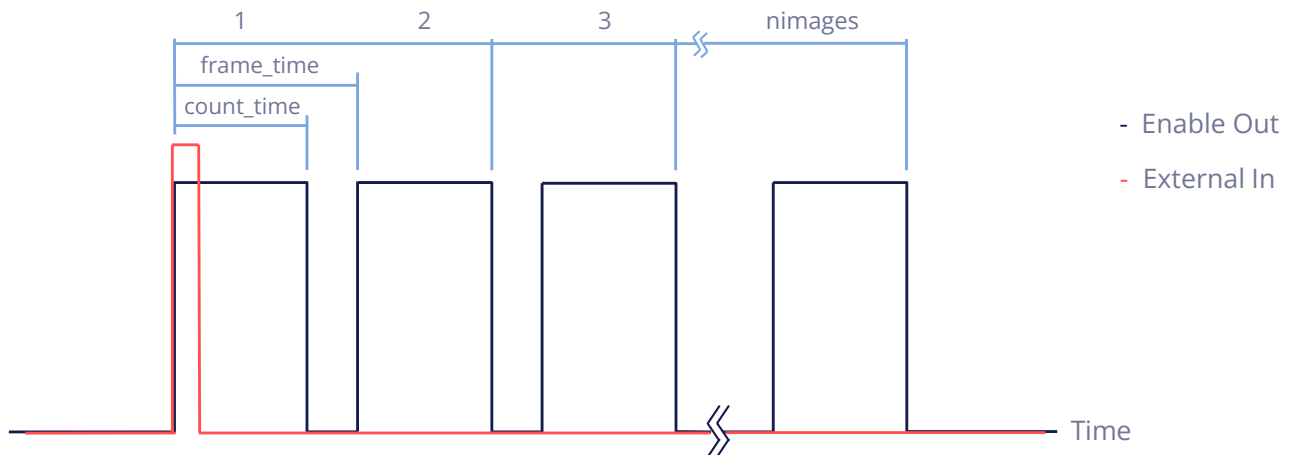


Figure 8.3: Exposure series defined by frame_time, count_time and nimages, triggered by a single external trigger pulse. Note that the periods are not drawn true to scale.

8.5. EXTE - Externally Enabled Exposure Series

Caution

#6



Consult the Technical Specifications for details about the required electrical characteristics of the trigger signal.

The ELA detector systems also support external enabling. In the external enable mode 'exte' a series of ntrigger frames can be recorded. The count time as well as the period of individual frames of a series are defined by the duration of the high state of the external enable signal. In all enable modes the detector configuration parameter nimages is implied to be 1. The number of frames in a series therefore is solely based on the value of the parameter ntrigger.

Information

#8



The configured count_time and frame_time should be close to the count time and frame time of the shortest expected exposure in the configured series. The set count_time will be used to calculate internal auto-summation configuration values (section 3.2.3). In most situations a reasonable estimate of these values is sufficient.

Example detector configuration for externally enabled exposure series:

detector config trigger_mode	{"value": "exte"}
detector config nimages	{"value": 1}
detector config ntrigger	{"value": 10}
detector config frame_time	{"value": 1.0} (see 8)
detector config count_time	{"value": 0.7} (see 8)

After arming the detector, the acquisition can be enabled by an external signal. The value `ntrigger` defines how often this can be repeated. The detector starts exposing the first image after the rising edge and stops after the falling edge of the external trigger signal. In the same manner, all subsequent frames are externally enabled. The count time and period are therefore solely determined by the external enable signal and the limitations of your detector system. The detector records as many frames as valid (according to the specifications) enable pulses are received until the value set for `ntrigger` is reached. Figure 8.4 illustrates a externally enabled series.

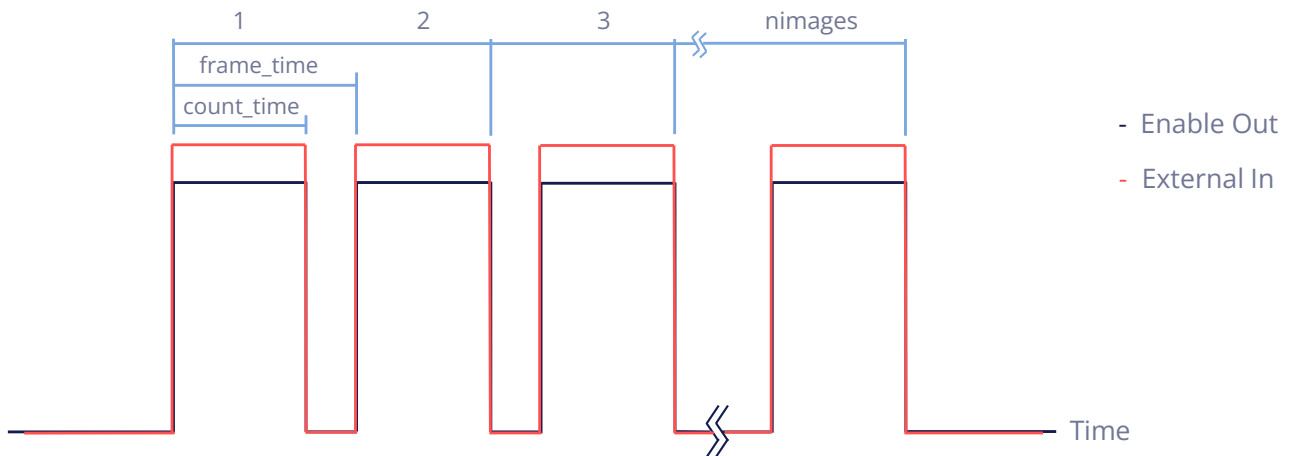


Figure 8.4: Exposures defined by external enable

9. HDF5 AND ALBULA

9.1. ALBULA Overview

ALBULA is a cross-platform image viewer developed and maintained by DECTRIS®. The Linux and Windows versions also provide an image library for the Python language.

ALBULA can be downloaded for free¹ at www.dectris.com. Scripts written in Python using ALBULA can be used to read, display and store data taken by the ELA detectors.

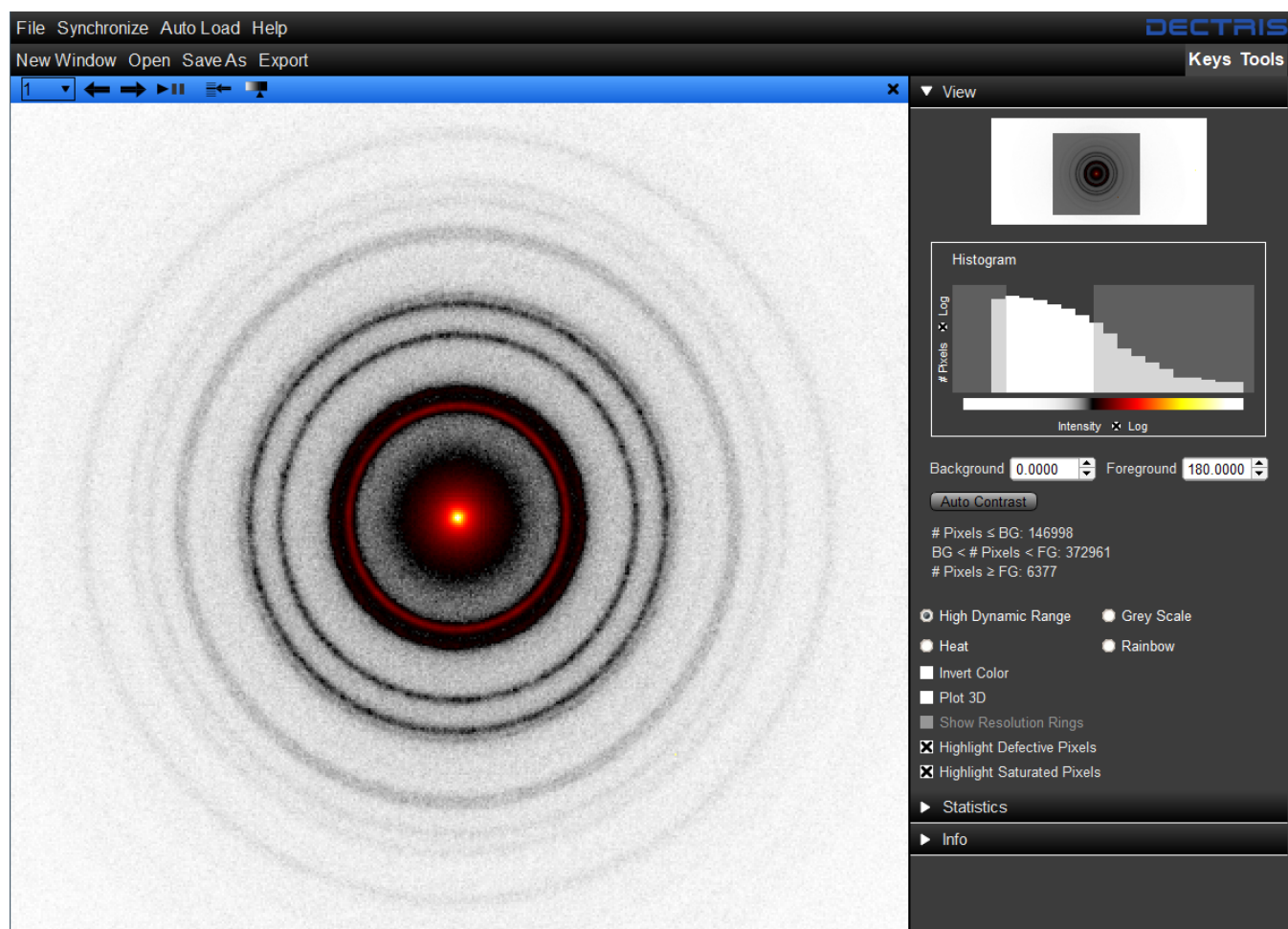


Figure 9.1: Screenshot of ALBULA showing an electron ring diffraction pattern acquired by an ELA

¹ Registration required

9.2. Third Party HDF5 Libraries

The ELA HDF5 data can also be directly read with programs using the HDF5 library. By default the ELA data is compressed using the BSLZ4² algorithm. In order to decompress the data, the HDF5 plug-in filter³ can be used, see repository <https://github.com/dectris/HDF5Plugin>. By setting the environment variable `HDF5_PLUGIN_PATH` to the path where the compiled plug-in filter can be found, the HDF5 library will decompress the data compressed with LZ4 by itself. If you want to use proprietary software like Matlab, IDL or similar, make sure that the HDF5 library version used by this software is at least v1.8.11 in order for the plug-in mechanism to work.

² See: <https://code.google.com/p/lz4/>, <https://github.com/kiyo-masui/bitshuffle>

³ In order to use the filter plug-in mechanism, HDF5 v1.8.11 or greater must be used.
See also <https://docs.hdfgroup.org/hdf5/rfc/HDF5DynamicallyLoadedFilters.pdf>

10. PIXEL MASK

10.1. Applying the pixel mask

The detector configuration parameter `pixel_mask_applied` enables (True) or disables (False) applying the pixel mask on the acquired data. For different `incident_energy` values these masks may differ from one another. If True (default), pixels which have any bit set in the `pixel_mask` are flagged with $(2^{\text{image bit depth}} - 1)$. Please consult the API Reference for details on the detector configuration parameter `pixel_mask`.

10.2. Updating the pixel mask

10.2.1. Overview

Updating the pixel mask of a ELA detector system involves four basic steps:

1. Retrieving the current pixel mask from the detector system via the SIMPLON API.
2. Manipulating the pixel mask to add or update pixels.
3. Uploading the updated pixel mask to the detector system via the SIMPLON API.
4. Persistently storing the updated pixel mask on the detector system by sending the detector command `arm`.

10.2.2. Retrieving the current mask from the detector system

The pixel mask can be retrieved from the detector system by a GET request on the detector configuration parameter `pixel_mask`. The data of the pixel mask is retrieved either as tiff or in JSON serialization by choosing `application/tiff` or `application/json` in the `get` request accordingly.

10.2.3. Manipulating the pixel mask

Information

#9



For details about the pixel values in the pixel mask and their meaning, consult the API Reference.

TIFF

If the pixel mask is retrieved and stored as `tiff`, the `uint32` data in the `tiff` file can be manipulated via Python.

JSON

If the pixel mask is retrieved as `JSON`, the HTTP reply has to be parsed correctly into an array. Please see the example below and the API Reference for details. The values in this array can then be manipulated to reflect the required updates of the pixel mask. After updating the array, it has to be serialized again in `JSON` according to the specifications in the API Reference.

10.2.4. Uploading and storing the pixel mask

The pixel mask is uploaded by sending a PUT request on the detector configuration parameter `pixel_mask` with the new mask as payload. After sending the detector command `arm`, the updated pixel mask is permanently stored on the detector system.

10.2.5. Python Example

The following Python code using common libraries provides a simple example for updating the pixel mask:

Python Code

```
import json
import numpy
import requests
from base64 import b64encode, b64decode

# Simple class to get/set a pixel mask or flatfield
class DMaskClient:
    def __init__(self, ip, port=80):
        self._ip = ip
        self._port = port

    def mask(self, mask):
        url = f'http://{self._ip}:{self._port}/detector/api/1.8.0/config/{mask}'
        darray = requests.get(url).json()['value']
        return numpy.frombuffer(b64decode(darray['data']),
                                dtype=numpy.dtype(str(darray['type']))).reshape(darray['shape'])

    def setMask(self, ndarray, mask):
        url = f'http://{self._ip}:{self._port}/detector/api/1.8.0/config/{mask}'
        data_json = json.dumps({'value': {
            '__darray__': (1,0,0),
            'type': ndarray.dtype.str,
            'shape': ndarray.shape,
            'filters': ['base64'],
            'data': b64encode(ndarray.data).decode('ascii') }})
        requests.put(url, data_json)

if __name__ == '__main__':
    # Create instance of the mask client
    maskClient = DMaskClient('169.254.254.1')

    # Get the pixel mask
    pixelMask = maskClient.mask('pixel_mask')

    # Copy the mask to writeable buffer, necessary for numpy>=1.16.0
    pixelMask = numpy.copy(pixelMask)
    # Set a new dead pixel [y,x]
    pixelMask[123, 234] = 2
    # Set a new noisy pixel [y,x]
    pixelMask[234, 123] = 8

    # Upload the updated pixel mask
    maskClient.setMask(pixelMask, 'pixel_mask')

    # Ensure that you 'arm' the detector to save the new pixel masks persistently
```

11. FLATFIELD

11.1. Applying the flatfield

The user is encouraged to use flatfields to counteract variations in the pixel-to-pixel sensitivity. Each flatfield consists of pixel-wise correction factors that are applied on the acquired data. The detector configuration parameter `flatfield_correction_applied` enables (True) or disables (False) applying the flatfield on the acquired data. Please consult the API Reference for details on the detector configuration parameter `flatfield`.

Information

#10



The factory calibration of the detector does not contain any flatfields. Therefore, it is the user's responsibility to provide meaningful flatfields in order to ensure optimal data quality.

11.2. Creating a flatfield

11.2.1. Overview

Creating a custom flatfield for the ELA detector system involves two basic steps:

1. Acquire uniformly-illuminated image via the SIMPLON API.
2. Upload pixel-wise correction factors via the SIMPLON API.

11.2.2. Acquire uniformly-illuminated image

Initialize the detector and set the detector configuration parameters to match the intended imaging conditions. Set up the microscope to produce a homogeneous illumination on the detector and acquire an image with at least 100,000 counts per pixel.

Information

#11



Flatfields are valid only for the given set of configuration parameters. Using flatfields recorded with different configuration parameters will have a negative impact on data quality.

The following Python code using common libraries provides a simple example on how to acquire a single flat-field image:

Python Code

```

if __name__ == '__main__':
    # Create detector instance
    client = DEigerClient('169.254.254.1')

    # Enable monitor interface
    client.setMonitorConfig('mode', 'enabled')

    # Set a long exposure time (e.g. 10s)
    client.setDetectorConfig('frame_time', 10)
    client.setDetectorConfig('count_time', 10)

    # Make sure flatfield correction is disabled
    client.setDetectorConfig('flatfield_correction_applied', False)

    # Arm, trigger and disarm the detector
    client.sendDetectorCommand('arm')
    client.sendDetectorCommand('trigger')
    client.sendDetectorCommand('disarm')

    # Save latest image to disk
    image = client.monitorSave('monitor', 'flatfield.tif')

```

11.2.3. Upload pixel-wise correction factors

The flatfield data on the detector is stored as a floating point array of pixel-wise correction factors that are multiplied with the recorded data. In case of an homogeneously-illuminated image, pixel-wise correction factors can be calculated by dividing the counts of each pixel by the median of the counts in the image. The flatfield on the detector is updated by sending a PUT request on the detector configuration parameter `flatfield` with the array of correction factors as data.

Information

#12



Uploaded flatfields are lost after (re-)initializing the detector or changing configuration parameters like e.g. `incident_energy` or `counting_mode`.

The following Python code demonstrate how to update the correction factors on the DCU with the `DMaskClient` from section 10.2:

[]\$_ Python Code

```
import tifffile
from DMaskClient import DMaskClient

# Create instance of DMaskClient
maskClient = DMaskClient('169.254.254.1')

# ... set the detector configuration parameters
# make sure applied_flatfield_correction is enabled

# read image with homogeneous illumination (> 100,000 counts per pixel)
dataFlatfield = tifffile.imread('flatfield.tif')

# Calculate pixel-wise correction factors
dataFlatfield = numpy.median(dataFlatfield) / dataFlatfield.astype('float32')

# Upload pixel-wise correction factors
maskClient.setMask(dataFlatfield, 'flatfield')

# ... continue with the acquisition
```

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